

Modular Interpretive Decompilation of Low-Level Code by Partial Evaluation

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joint work with

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Introduction

Motivation

Low-level code \Rightarrow Intermediate representations

- **Mobile environments:** only *low-level code* available.
- Analysis tools unavoidably more complicated.
 - ▶ unstructured control flow,
 - ▶ use of operand stack,
 - ▶ use of heap, etc.

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- Decompiling to intermediate representations:
 - ▶ abstracts away particular language features.
 - ▶ simplifies development of analyzers, model checkers, etc.
 - ▶ variants: *clause-based*, *BoogiePL*, *Soot*, etc.

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High-level (declarative) languages

- Convenient intermediate representation:
 - ▶ iterative constructs (loops) \Rightarrow *recursion*.
 - ▶ all variables in *local scope* of methods represented uniformly.
- Advanced tools (for declarative) languages re-used.

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Interpretive Decompilation

- Most of the approaches develop hand-written decompilers.
- Appealing alternative: **interpretive decompilation**
- PE allows specializing a program w.r.t. some part of its input.

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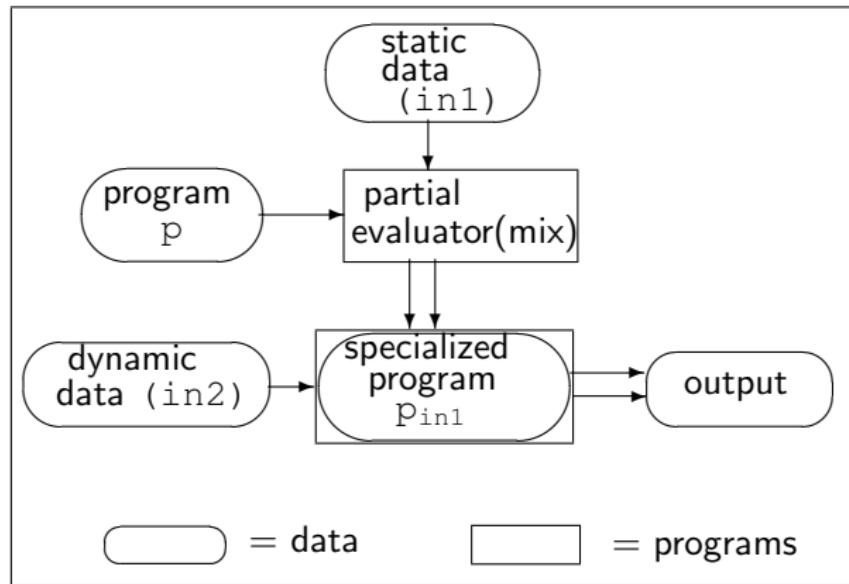
Definition (1st Futamura Projection)

A program P written in L_S can be compiled into another language L_O by specializing an interpreter for L_S written in L_O w.r.t. P .

First Futamura Projection

Partial Evaluation and the Interpretive Approach

$$p(\text{in}1, \text{in}2) = \text{output}$$

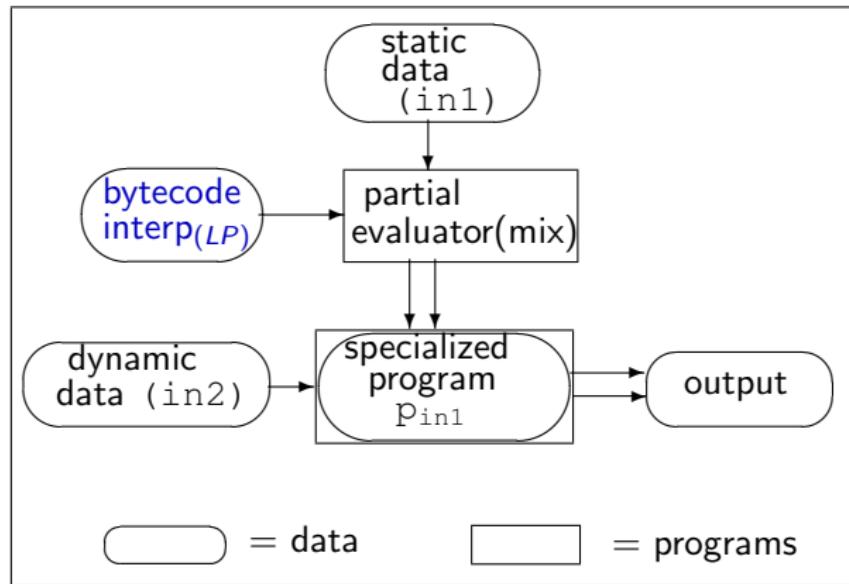


$$[[p]] [\text{in}1, \text{in}2] = [[[[\text{mix}]] [p, \text{in}1]]] [\text{in}2]$$

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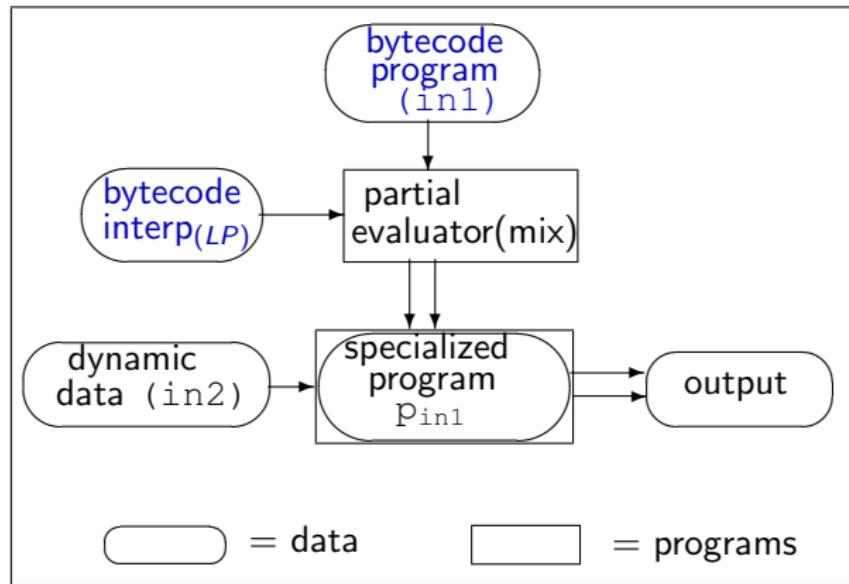


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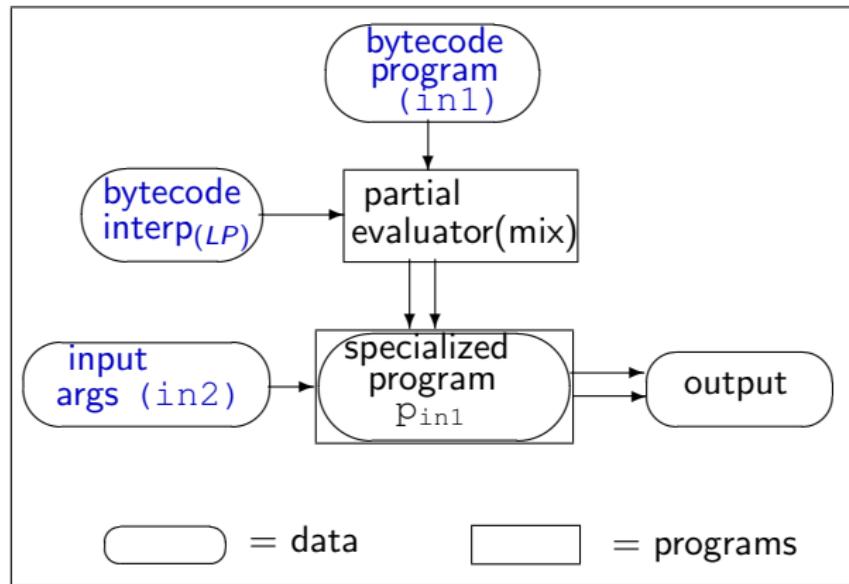


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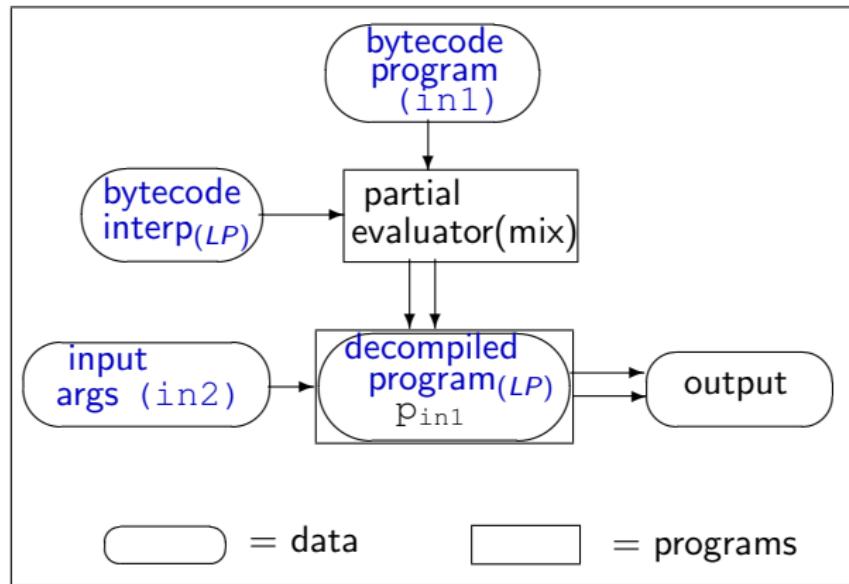


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bytecode interpreter

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main(Method,InArgs,Top) :-  
    build_s0(InArgs,S0),  
    execute(S0,Sf),  
    Sf = st(.,[Top|_],_)).  
  
step(push(X),S1,S2) :-  
    S1 = st(PC,S,L)),  
    next(PC,PC2),  
    S2 = st(PC2,[X|S],L)).  
  
execute(S1,Sf) :-  
    S1 = st(PC,_,_),  
    bytecode(PC,Inst,_),  
    step(Inst,S1,S2),  
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step(store(X),S1,S2) :-  
    S1 = st(PC,[I|S],LV)),  
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```

Decompiled code

```
main(gcd,[X,0],X).           exec_1(Y,0,Y).  
main(gcd,[X,Y],Z) :- Y \= 0,   exec_1(Y,R,Z) :- R \= 0,  
R is X rem Y, exec_1(Y,R,Z).  R' is Y rem R, exec_1(R,R',Z).
```

Contributions in Interpretive Decompilation

Advantages w.r.t. dedicated (de-)compilers:

- flexibility: interpreter easier to modify;
- more reliable: easier to trust that the semantics preserved;
- easier to maintain: new changes easily reflected in interpreter;
- easier to implement: provided a partial evaluator is available.

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Only proofs-of-concept in interpretive decompilation:

- e.g. in [PADL'07] we decompile a subset of Java Bytecode to Prolog.
- Open issues we have answered in this work:
 - ▶ **Scalability**: first *modular* decompilation scheme by PE
 - ▶ **Structure preservation**: of the original program
 - ▶ **Quality**: equivalent to hand-written decompilers

Conclusions and Future Work

- We have provided mechanisms to positively answer these issues:
 - ▶ Method optimality: Code for each method is decompiled only once ⇒ **Big-step interpreter** and **PE annotations**.
 - ▶ Block optimality: Code for each instruction is emitted and evaluated at most once ⇒ **PE annotations** and **pre-analysis**.

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- Implemented an interpretive decompiler of Java Bytecode to Prolog.
- Future work: Special handling for the heap, exploit instrumented decompilation, improve efficiency, applications, etc.

Question to SCAM Audience

- Are we happy with hand-written decompilers or we would like more flexible approaches?

Contributions

Contribution 1

- *Modular* decompilation: decompile a method at a time
- First *modular* decompilation scheme by PE:
 - ▶ compositional treatment to method invocation ⇒ consider a *big-step* interpreter;
 - ▶ “residualize” calls in decompiled program, we automatically generate program annotations for this purpose;

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- First *modular* decompilation scheme by PE:
 - ▶ compositional treatment to method invocation \Rightarrow consider a *big-step* interpreter;
 - ▶ “residualize” calls in decompiled program, we automatically generate program annotations for this purpose;

Proposition (modular optimality)

We decompile the code corresponding to each method in P_{bc} exactly once.

Decompilation of Low-level Code

Contribution 2

- Is possible to obtain by interpretive decompilation programs whose **quality** is equivalent to dedicated decompilers?
- Idea: since decompilers first build a *CFG* for the method, study how a similar notion can be used for controlling PE of the interpreter
- **Block-level decompilation** produce a rule for each block in the *CFG*.

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- Idea: since decompilers first build a *CFG* for the method, study how a similar notion can be used for controlling PE of the interpreter
- **Block-level decompilation** produce a rule for each block in the *CFG*.

Proposition (block optimality)

- ① residual code for each bytecode instruction emitted once;
- ② each bytecode instruction evaluated at most once;

Conclusions and Future Work

- Open issues: scalability, structure preservation, quality ...
- We have provided mechanisms to positively answer these issues:
 - ▶ Method optimality: Code for each method is decompiled only once ⇒ **Big-step semantics** and **PE annotations**.
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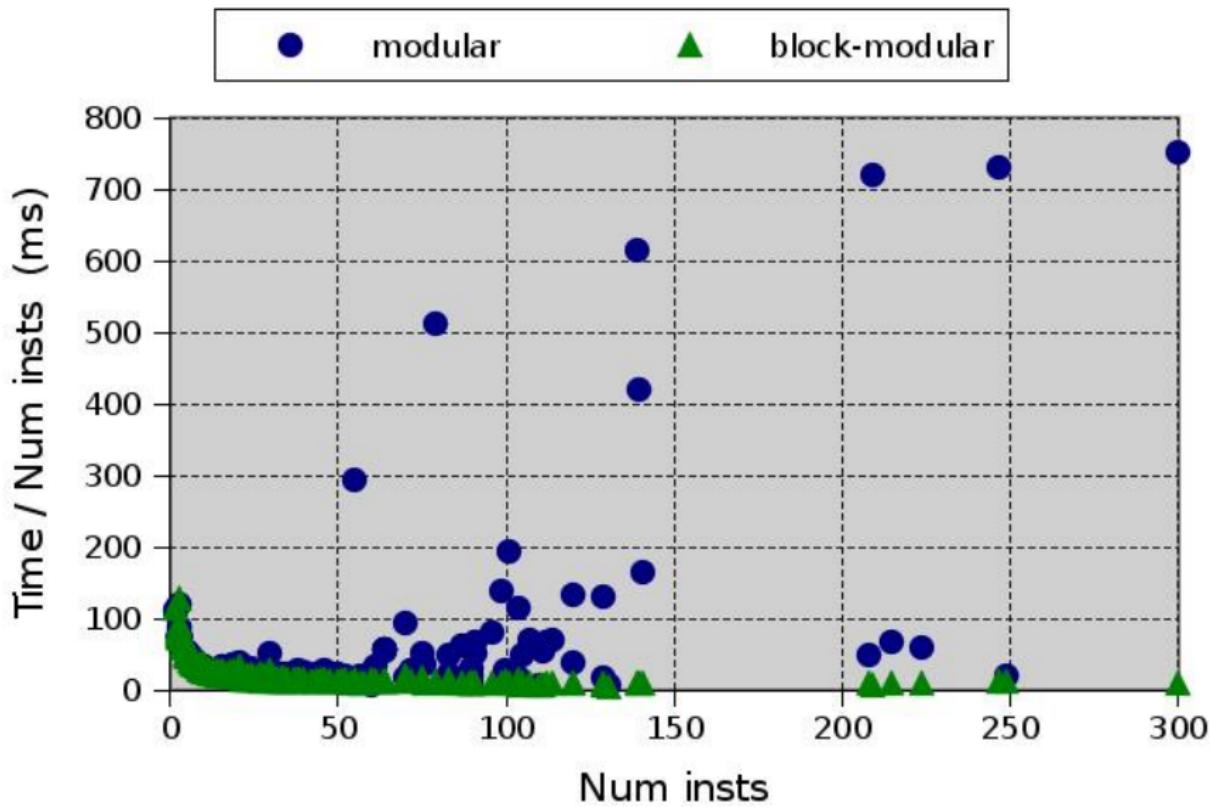
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- Average improvements: **10 times faster** decompilations and **5 times smaller** decompiled program sizes (even we get ∞ gains).

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Experimental Evaluation (JOlden benchmarks suite)



Intraprocedural Decomposition

- We consider the \mathcal{L}_{bc} -bytecode language ($\mathcal{L}_{bc} \subset \text{Java bytecode}$).

$$\text{Inst} ::= \text{push}(x) \mid \text{load}(v) \mid \text{store}(v) \mid \text{add} \mid \text{sub} \mid \text{mul} \mid \text{div} \mid \text{rem} \mid \text{neg} \mid \text{if } \diamond(\text{pc}) \mid \text{if0 } \diamond(\text{pc}) \mid \text{goto}(\text{pc}) \mid \text{return}$$

- State $\equiv \langle PC, OpStack, LocalVars \rangle$

The \mathcal{L}_{bc} -bytecode interpreter

```

main(Method, InArgs, Top) :- build_s0(InArgs, S0),
                           execute(S0, Sf),
                           Sf = st(_, [Top|_], _).

execute(S, S) :- S = st(PC, [-Top|_], _),
                bytecode(PC, return, _).

execute(S1, Sf) :- S1 = st(PC, _, _),
                  bytecode(PC, Inst, _),
                  step(Inst, S1, S2),
                  execute(S2, Sf).

step(push(X), S1, S2) :- S1 = st(PC, S, L),
                           next(PC, PC2),
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step(store(X), S1, S2) :- S1 = st(PC, [I|S], LV),
                           next(PC, PC2),
                           localVar_update(LV, X, I, LV2),
                           S2 = st(PC2, S, LV2).

step(goto(PC), S1, S2) :- S1 = st(_, S, LV),
                           S2 = st(PC, S, LV).

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Unfolding trees

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main(gcd,[X,Y],Z)
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exec(st(0,[],[X,Y,0]),S_f)
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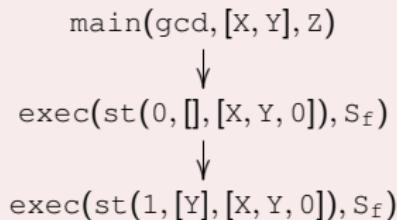
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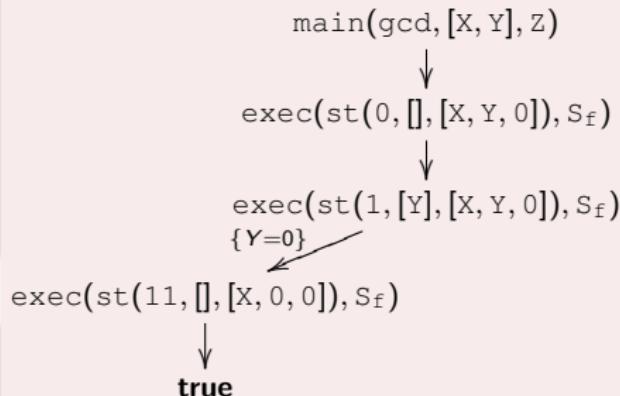
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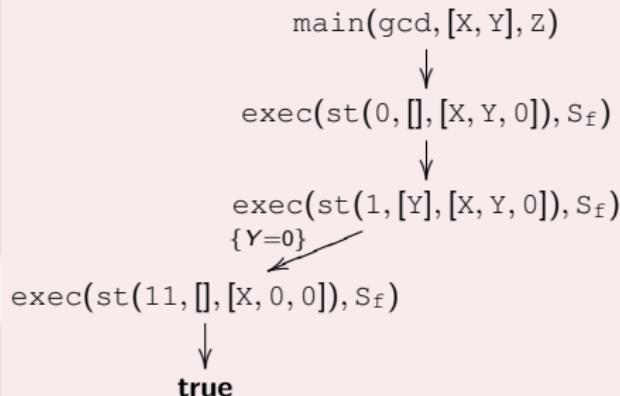
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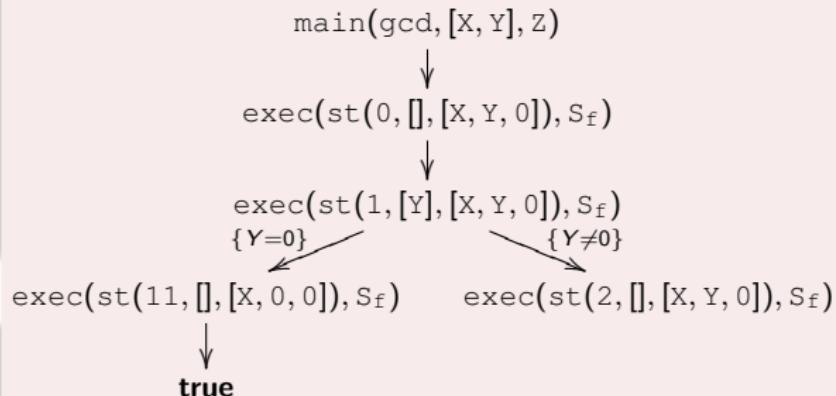
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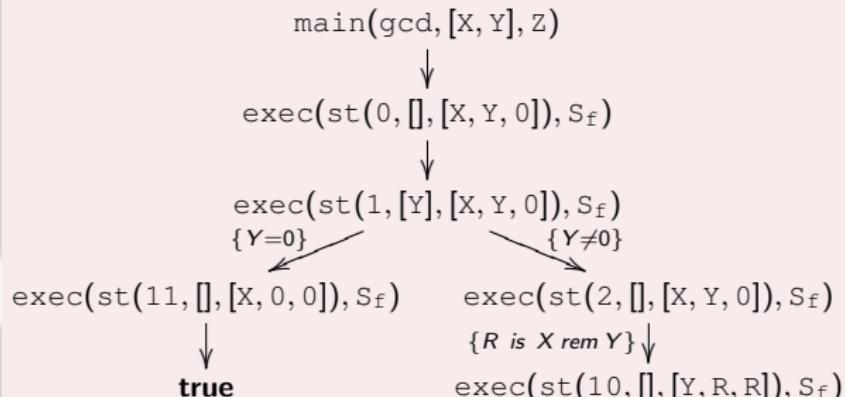
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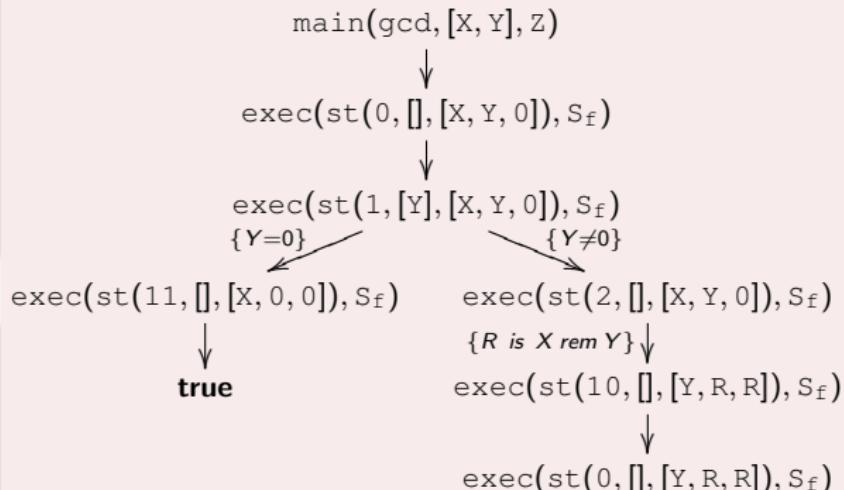
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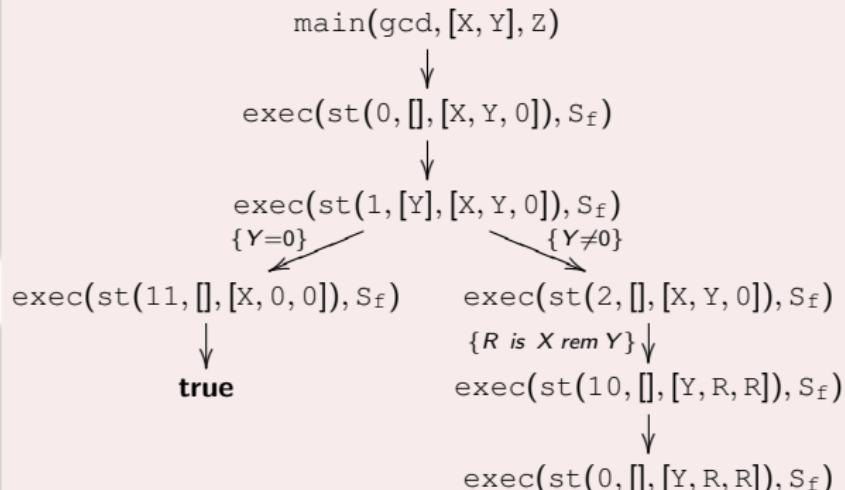
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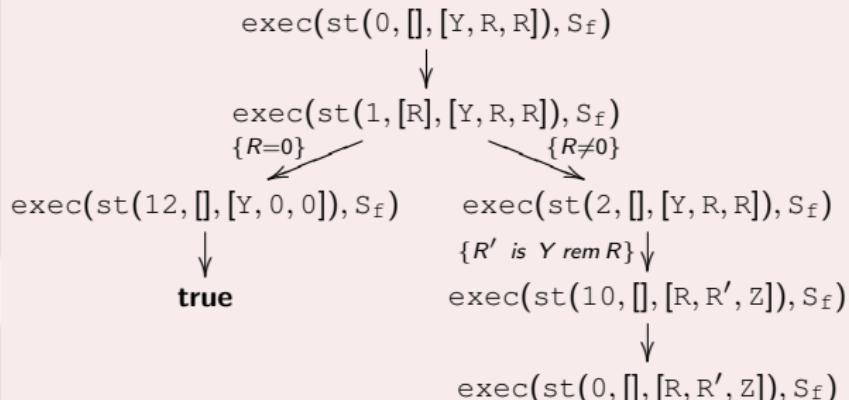
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Unfolding trees



Decompiled code

```
main(gcd, [X, 0], X).  
main(gcd, [X, Y], Z) :- Y \= 0,  
    R is X rem Y, exec1(Y, R, Z).
```

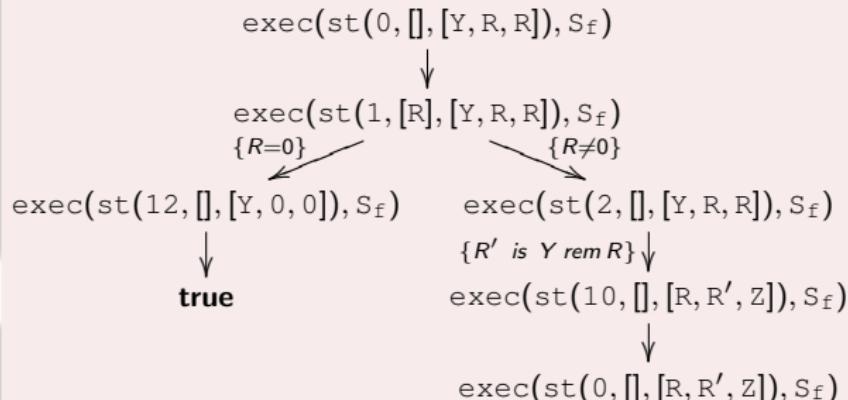
Example 1: Source code

```
int gcd(int x,int y){  
    int res;  
    while (y != 0){  
        res = x mod y;  
        x = y;  
        y = res;}  
    return x;}
```

 \mathcal{L}_{bc} -bytecode

0:load(1)	7:store(0)
1:if0eq(11)	8:load(2)
2:load(0)	9:store(1)
3:load(1)	10:goto(0)
4:rem	11:load(0)
5:store(2)	12:return
6:load(1)	

Unfolding trees



Decompiled code

```
main(gcd,[X,0],X).           exec_1(Y,0,Y).  
main(gcd,[X,Y],Z) :- Y \= 0,   exec_1(Y,R,Z) :- R \= 0,  
                  R is X rem Y. exec_1(Y,R,Z).   R' is Y rem R. exec_1(R,R',Z).
```

Example 1: Source code

```
int gcd(int x,int y){  
    int res;  
    while (y != 0){  
        res = x mod y;  
        x = y;  
        y = res;}  
    return x;}
```

\mathcal{L}_{bc} -bytecode

```
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```

Example 1: Source code

```
int gcd(int x,int y){  
    int res;  
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        x = y;  
        y = res;}  
    return x;}
```

Unfolding trees

```
main(gcd,[X,Y],Z)
```

 \mathcal{L}_{bc} -bytecode

```
0:load(1) 7:store(0)  
1:if0eq(11) 8:load(2)  
2:load(0) 9:store(1)  
3:load(1) 10:goto(0)  
4:rem 11:load(0)  
5:store(2) 12:return  
6:load(1)
```

Decompiled code

Example 1: Source code

```
int gcd(int x,int y){  
    int res;  
    while (y != 0){  
        res = x mod y;  
        x = y;  
        y = res;}  
    return x;}
```

Unfolding trees

```
main(gcd,[X,Y],Z)  
↓  
exec(st(0,[],[X,Y,0]),S_f)
```

 \mathcal{L}_{bc} -bytecode

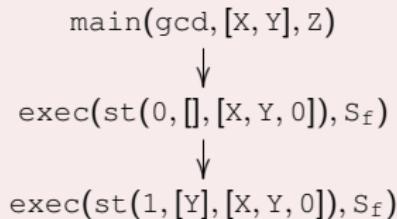
```
0:load(1) 7:store(0)  
1:if0eq(11) 8:load(2)  
2:load(0) 9:store(1)  
3:load(1) 10:goto(0)  
4:rem 11:load(0)  
5:store(2) 12:return  
6:load(1)
```

Decompiled code

Example 1: Source code

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int gcd(int x,int y){  
    int res;  
    while (y != 0){  
        res = x mod y;  
        x = y;  
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```

Unfolding trees

 \mathcal{L}_{bc} -bytecode

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3:load(1)    10:goto(0)  
4:rem        11:load(0)  
5:store(2)   12:return  
6:load(1)
```

Decompiled code

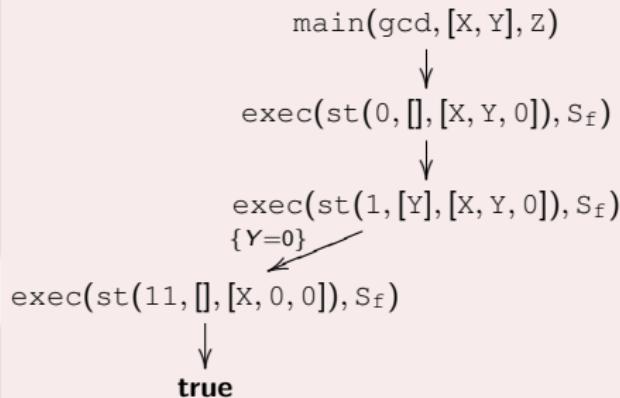
Example 1: Source code

```
int gcd(int x,int y){  
    int res;  
    while (y != 0){  
        res = x mod y;  
        x = y;  
        y = res;}  
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 \mathcal{L}_{bc} -bytecode

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4:rem	11:load(0)
5:store(2)	12:return
6:load(1)	

Unfolding trees



Decompiled code

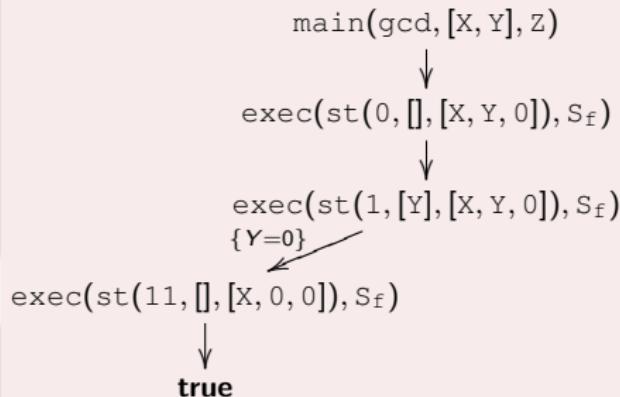
Example 1: Source code

```
int gcd(int x, int y){  
    int res;  
    while (y != 0){  
        res = x mod y;  
        x = y;  
        y = res;}  
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```

 \mathcal{L}_{bc} -bytecode

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5:store(2)	12:return
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Unfolding trees



Decompiled code

```
main(gcd, [X, 0], X).
```

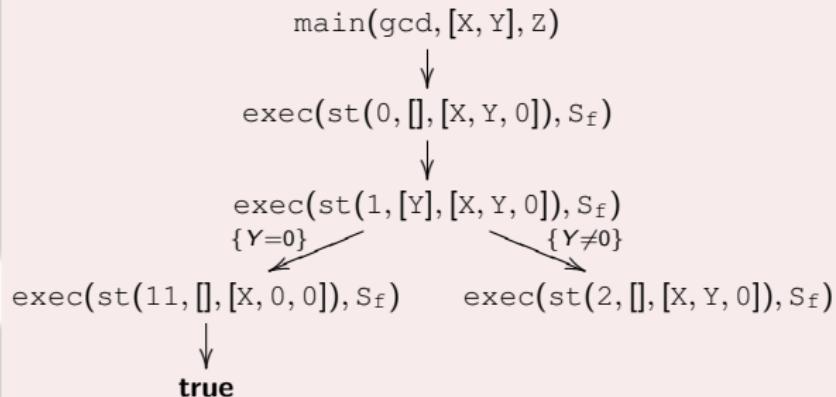
Example 1: Source code

```
int gcd(int x, int y){  
    int res;  
    while (y != 0){  
        res = x mod y;  
        x = y;  
        y = res;}  
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 \mathcal{L}_{bc} -bytecode

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```

Unfolding trees



Decompiled code

```
main(gcd, [X, 0], X).
```

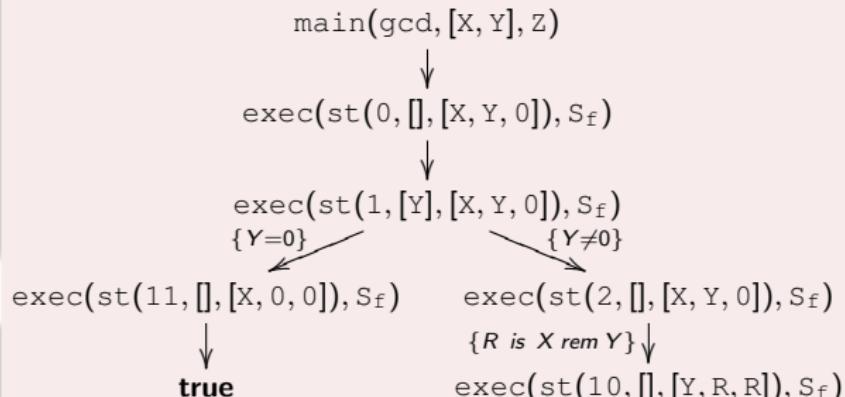
Example 1: Source code

```
int gcd(int x, int y){  
    int res;  
    while (y != 0){  
        res = x mod y;  
        x = y;  
        y = res;}  
    return x;}
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 \mathcal{L}_{bc} -bytecode

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5:store(2)   12:return  
6:load(1)
```

Unfolding trees



Decompiled code

```
main(gcd, [X, 0], X).
```

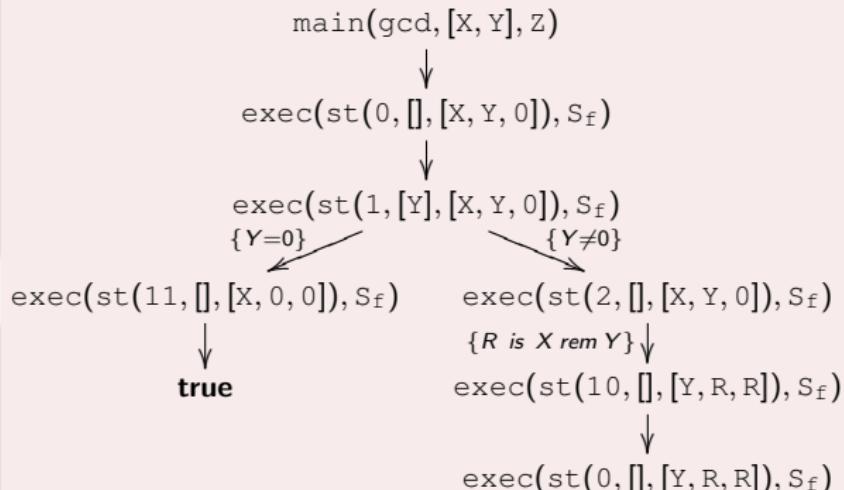
Example 1: Source code

```
int gcd(int x, int y){  
    int res;  
    while (y != 0){  
        res = x mod y;  
        x = y;  
        y = res;}  
    return x;}
```

 \mathcal{L}_{bc} -bytecode

```
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4:rem  
5:store(2)   11:load(0)  
6:load(1)    12:return
```

Unfolding trees



Decompiled code

```
main(gcd, [X, 0], X).
```

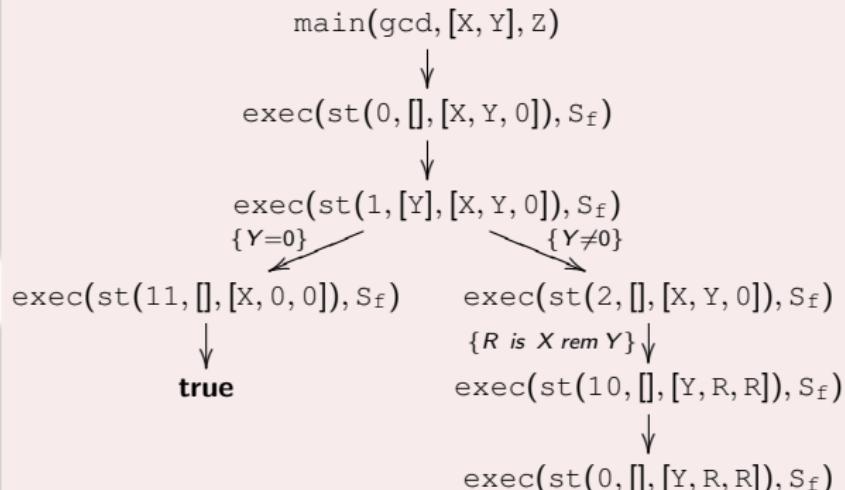
Example 1: Source code

```
int gcd(int x, int y){  
    int res;  
    while (y != 0){  
        res = x mod y;  
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 \mathcal{L}_{bc} -bytecode

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```

Unfolding trees



Decompiled code

```
main(gcd, [X, 0], X).  
main(gcd, [X, Y], Z) :- Y \= 0,  
    R is X rem Y, exec1(Y, R, Z).
```

Example 1: Source code

```
int gcd(int x,int y){  
    int res;  
    while (y != 0){  
        res = x mod y;  
        x = y;  
        y = res;}  
    return x;}
```

Unfolding trees

```
exec(st(0,[],[Y,R,R]),Sf)
```

 \mathcal{L}_{bc} -bytecode

```
0:load(1)    7:store(0)  
1:if0eq(11)  8:load(2)  
2:load(0)    9:store(1)  
3:load(1)    10:goto(0)  
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Decompiled code

```
main(gcd,[X,0],X).  
main(gcd,[X,Y],Z) :- Y \= 0,  
                  R is X rem Y, exec1(Y,R,Z).
```

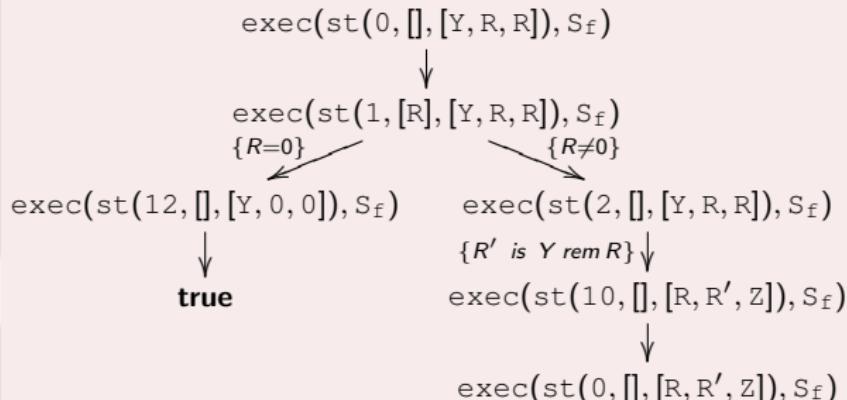
Example 1: Source code

```
int gcd(int x,int y){  
    int res;  
    while (y != 0){  
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        x = y;  
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Unfolding trees



Decompiled code

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    R is X rem Y, exec1(Y, R, Z).
```

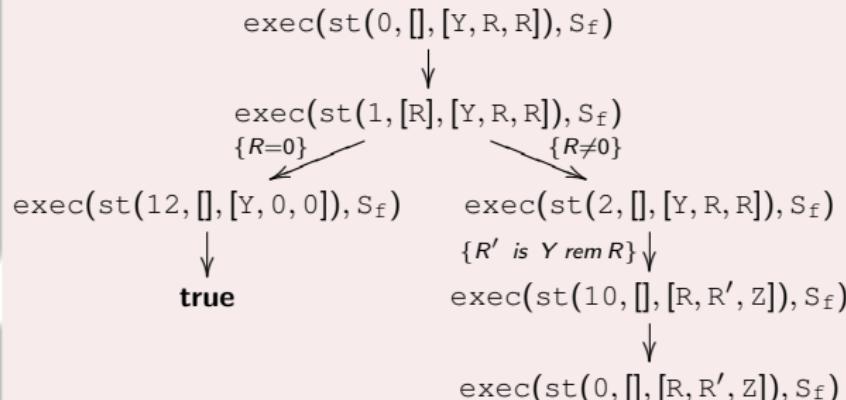
Example 1: Source code

```
int gcd(int x,int y){  
    int res;  
    while (y != 0){  
        res = x mod y;  
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Unfolding trees



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```
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                  R is X rem Y. exec_1(Y,R,Z).   R' is Y rem R. exec_1(R,R',Z).
```